Random numbers and Monte Carlo techniques

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Random numbers

- What is a random number?
 - Is 3 a random number?
- Random numbers always come in sequences
- Why do we need random numbers?
 - to calculate integrals!



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What is a good random number?

- Random numbers are "uniform"
 - uniformity: numbers are equally probable everywhere
- Random numbers are "unpredictable"
 - independence: current value is not related to previous values
- Random numbers are not like this:



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Random number tests

- Making sure that random numbers are random is a big deal https://csrc.nist.gov/projects/random-bit-generation/ documentation-and-software/guide-to-the-statistical-tests
- We can't define what a random sequence is, only what it isn't
- General approach: calculate some properties of the random sequence (number of 1's and 0's, length of groups consisting of 1's, etc), compare with prediction for a "true" random sequence

Procedure:

- null hypothesis: the sequence is random
- carry out the testing procedure
- ► calculate the *P*-value
- the sequence is declared random (null hypothesis is successful) if $\mathcal{P} \ge \alpha$, where α is a predefined value (e.g. 0.01 for 99% C.L.)
- Popular tests: χ^2 , Kolmogorov-Smirnov

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Random number tests (2)

• χ^2 test

suppose we have n possible categories of observations, in each category i we expect e_i occurrences and observe o_i occurrences, then

$$\chi^2 = \sum_{i=1}^n \frac{(o_i - e_i)^2}{e_i}$$

is distributed as χ^2 with n-1 degrees of freedom

• χ^2 should be less than certain value

Kolmogorov-Smirnov test

- ▶ suppose F(x) is cumulative distribution function (c.d.f.) $F(x) = \int_{-\infty}^{x} f(x) dx$ where f(x) is probability density function (pdf)
- compare observed and expected cdf (usually in bins of x)
- ► calculate maximum deviations $K^+ = \sqrt{n} \max_x (F_o(x) - F_e(x))$ $K^- = \sqrt{n} \max_x (F_e(x) - F_o(x))$
- K^+ , K^- should be less than certain value

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Methods to generate random numbers

- Hardware random number generators
 - radioactivity, cosmic rays, thermal noise
- /dev/random
 - "entropy harvesting": collect environmental noise from LAN traffic, serial line traffic, HW and SW interrupts etc.
- Pseudo random generators

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Pseudo random generators

• Linear congruential generators LCG(m, a, c, x₀)

$$x_{i+1} = (ax_i + c) \mod m$$

- If (and only if)
 - c is relatively prime to m,
 - ► a 1 is a multiple of p, for every prime p dividing m, and
 - ▶ a 1 is a multiple of 4, if p is a multiple of 4,

then LCG has a period of m

- LCG may or may not be good
 - infamous example: IBM generator RANDU, LCG(2³¹,65539,0,1)



Mersenne Twister

- State-of-the-art in random number generation (since 1997)
 ROOT: TRandom3
- Very fast and short (but not very easy to understand)
- Period is a Mersenne number (a prime number of the form $2^m 1$; for the popular implementation, m = 19937)
- Can be improved (cf SFMT)

Integer and floating point random numbers

- Random number generators produce sequences of integers r_i , $0 \le r_i < MAX$
- We are usually interested in real random numbers that follow some distribution
- Integer to uniform: pick $MAX = 2^p$, p=precision (e.g. 32), then $q_i = r_i/MAX$ is uniform on (0,1) (and $a + (b a)q_i$ is uniform on (a, b)

Generating distributions (1)

- Gaussian distribution: Box-Muller transform
 - if u_1 , u_2 are independent random variables uniform on (0,1), then $\sqrt{-2 \ln x_1} \cos(2\pi x_2)$, $\sqrt{-2 \ln x_1} \sin(2\pi x_2)$ are independent random variables with normal distribution ($x_0 = 0$, $\sigma = 1$)
- Gaussian distribution, multivariate case with covariance matrix V:
 - generate n independent Gaussian variables g with mean 0 and variance 1 as above
 - x = ⟨x⟩ + Lg where L is the (unique) lower triangular matrix that satisfies V = LL^T, it can be found using Cholesky's decomposition

Generating distributions (2)

- Poisson distribution with mean λ : Knuth's algorithm
 - \blacktriangleright count the number of times you multiply uniform random numbers until the product becomes less than $e^{-\lambda}$

```
int poissonRandomNumber(int lambda) {
    double L = Math.exp(-lambda);
    int k = 0;
    double p = 1;
    do {
        k = k + 1;
        double u = Math.random();
        p = p * u;
    } while (p > L);
    return k - 1;
}
```

- $\bullet\,$ if λ is large, the algorithm takes too long to complete
 - Gaussian is a good approximation

Generating distributions (3)

- Isotropic direction in 3d:
 - "isotropic" = density proportional to solid angle dΩ = dφ sinθ dθ = −dφ d(cos θ)
 - $\cos \theta$ is uniform on (-1,1) and φ is uniform on $(0,2\pi)$

. . . etc.

• What to do for an arbitrary distribution?

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Acceptance-rejection

- The algorithm:
 - encapsulate the p.d.f. f(x) in a box a < x < b, $0 < f(x) < f_{max}$
 - generate a random number x uniform on (a, b)
 - generate a random number y uniform on $(0, f_{max})$
 - accept x as result if y < f(x)
- Can be easily implemented for binned p.d.f.
- Problems:
 - doesn't work for $-\infty < x < +\infty$
 - inefficient for pole-like functions
- Possible improvements: split the x range in subranges, each with its own f_{max} ("adaptive rejection") – improves efficiency

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Inverse transform

- Based on the fact that c.d.f. $F(x) == \int_a^x f(x) dx$ is by itself a random variable uniform on (0,1)
- The algorithm:
 - generate a random number y uniform on (0,1)
 - ► solve for x the equation $\frac{\int_a^x f(x)dx}{\int_a^b f(x)dx} = y$
- Handy if it's easy to find $F^{-1}(y)$
- Can be easily implemented for binned c.d.f.

Weights

- What if acception-rejection is impractical and inverting the integral is too much work?
- We can do weighted Monte Carlo
- The algorithm:
 - approximate the "bad" function f(x) with a "good" function $f^*(x)$
 - generate a random number x with p.d.f. $f^*(x)$
 - assign weight $w = \frac{f(x)}{f^*(x)} \sim 1$
 - two options: do acceptance-rejection based on w/w_{max} (less efficient) or count "events" taking the weights into account

Multidimensional case

- It helps if the variables are separable (and therefore uncorrelated): $f(x_1, ..., x_n) = \prod_{i=1}^n f_i(x_i)$
- Otherwise, distribution along each dimension has to be calculated
- There are special methods to do it efficiently

Metropolis-Hastings algorithm

- This is an example of Markov Chain Monte Carlo
- It doesn't require p.d.f. f(x) to be normalized to 1 it will work with any function proportional to p.d.f.
- The algorithm:
 - ▶ pick a "proposal p.d.f." q(x', x) which gives the probability for the next candidate x' provided the current sample value is x. q(x', x) can be arbitrary (provided q(x', x) = q(x, x')), the usual choice is a (multivariate) Gaussian centered at x
 - pick a starting point x₀ (again, it can be arbitrary)
 - at each step, given current state x, generate next candidate state x' according to q(x', x)
 - calculate the "acceptance ratio" $\alpha = f(x')/f(x)$
 - if α > 1 then the new state is more probable than the old one accept it (i.e. assign x' to x)
 - ▶ otherwise, generate a random number u uniform on (0,1) and accept the new state if $\alpha > u$
 - otherwise, repeat with the old state x
- The Metropolis-Hastings algorithm is very close to simulated annealing a minimization heuristic
 - Both methods work very well in highly multidimensional cases